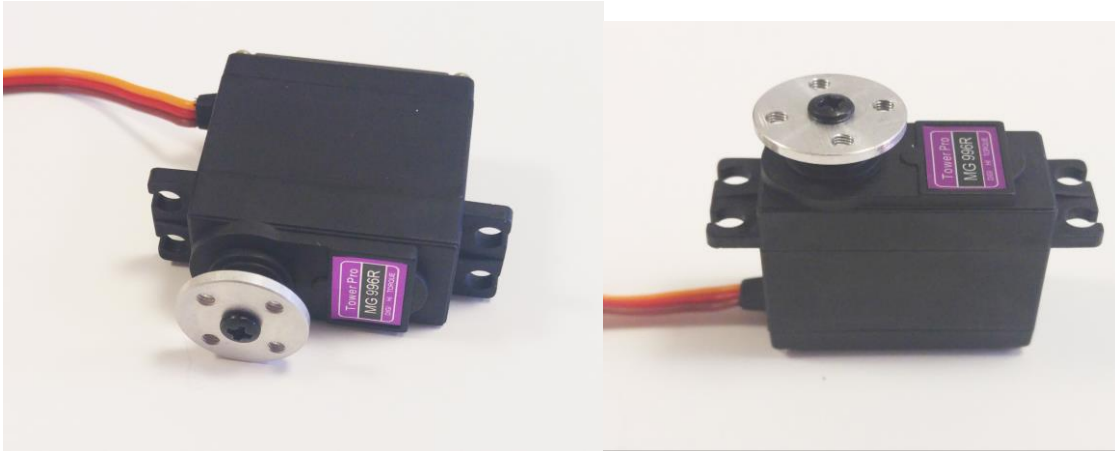


## 6 DOF Robot Arm Installation Diagram

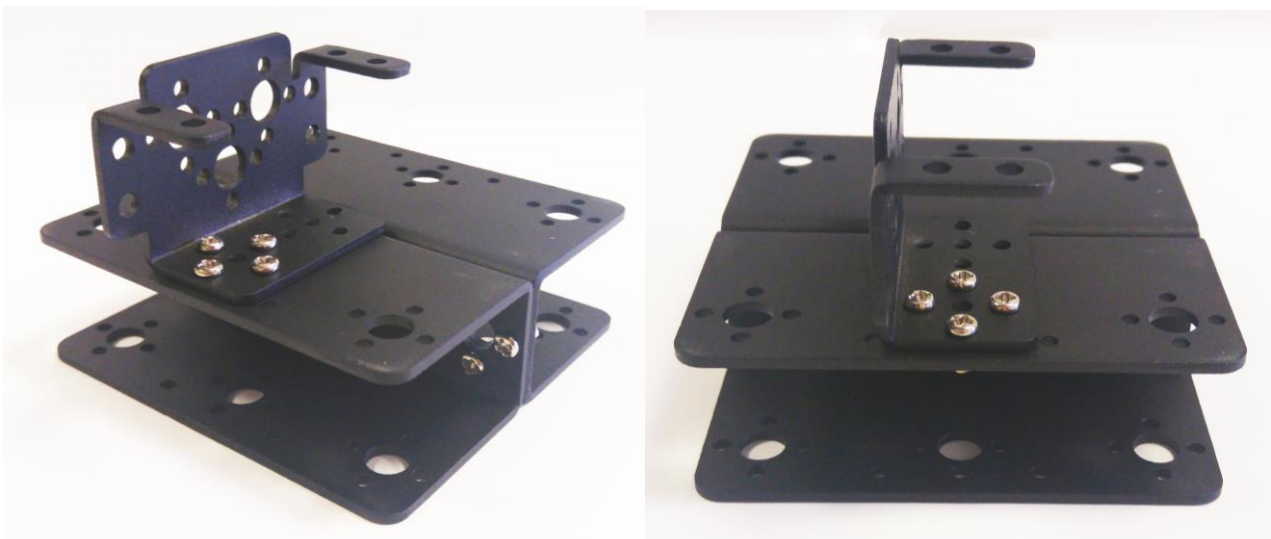
Install five servos on the servos base, and tighten the screws.



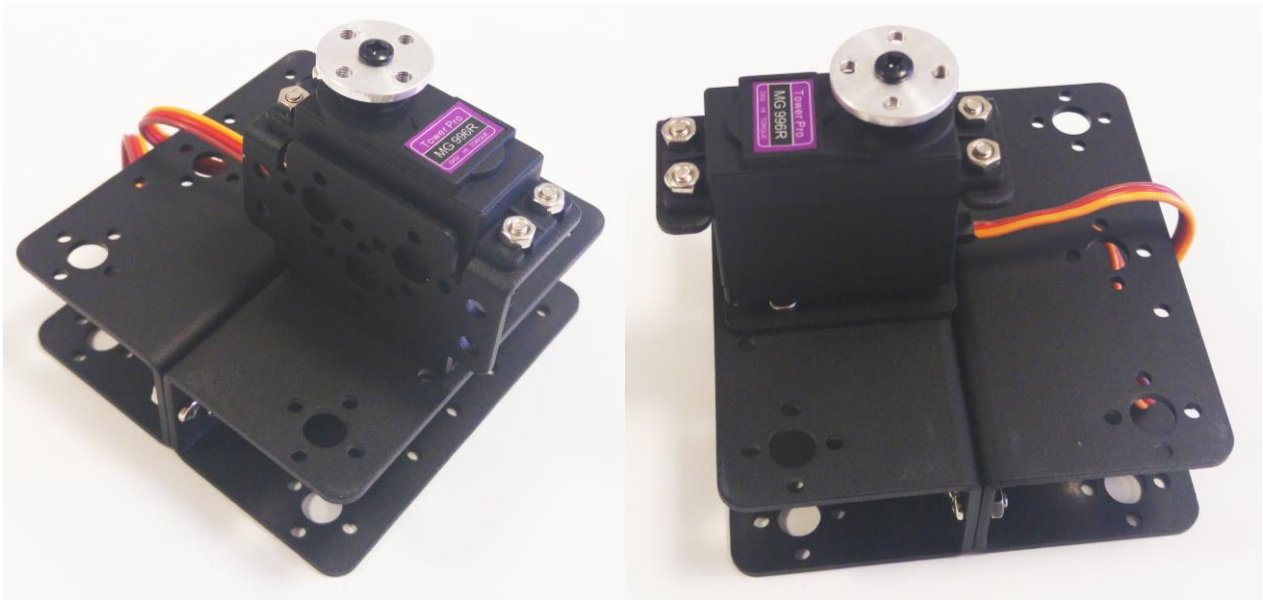
First, fix the two U-shaped together.



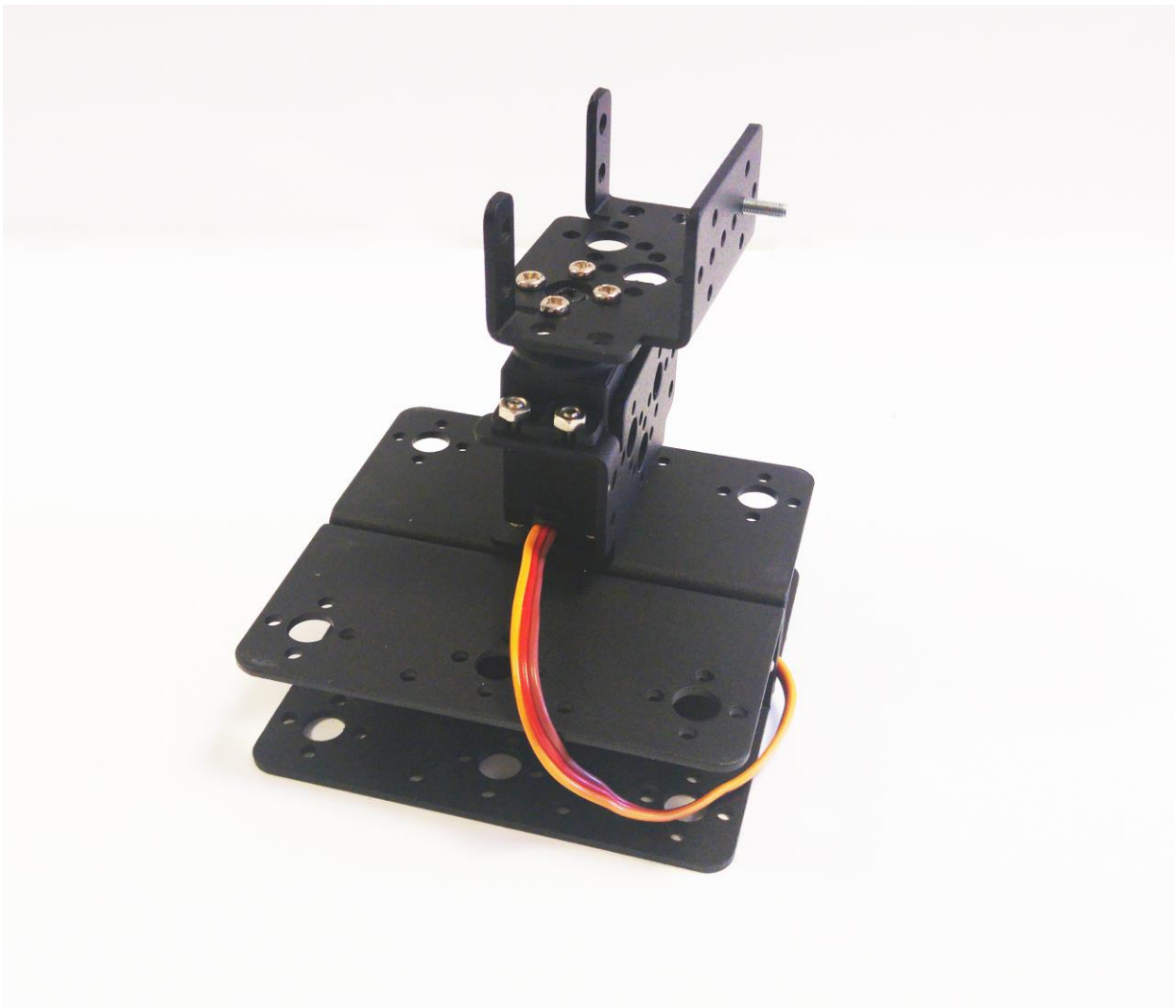
Second, fix the multi-function bracket on the beams. (attention the direction)



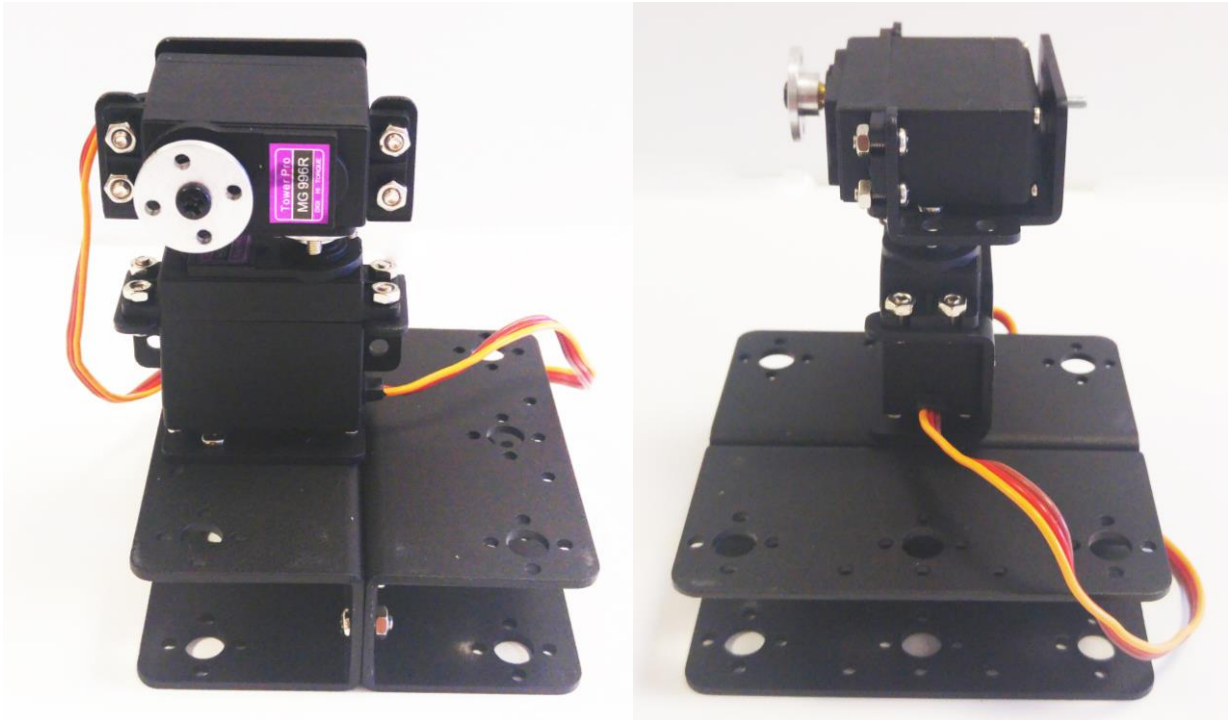
The third step, The servos is mounted on the multi-bracket. (attention the direction)



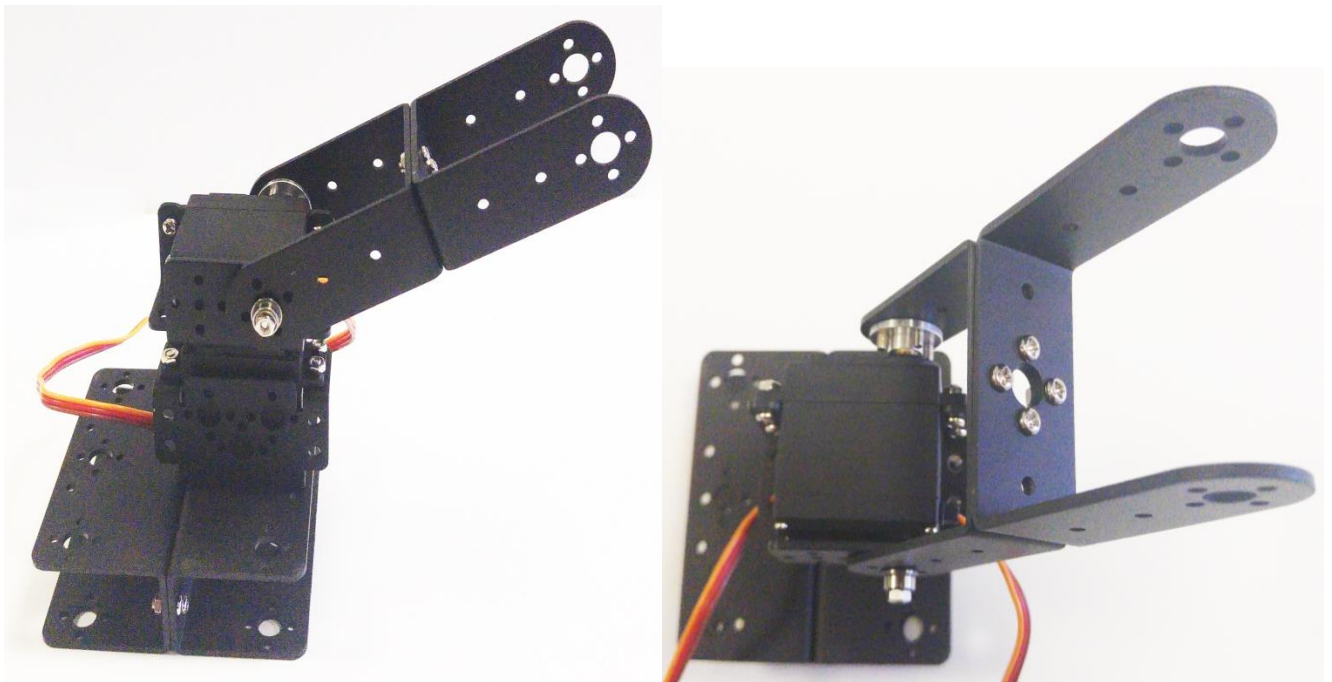
The fourth step, fix a multi-bracket on the servos and insert the M3\*10 screw in the middle of the left side.



The fifth step, fix the servos.



The sixth step, fix the long U-shaped on the servos and install the bearing. And fix the same long U-shaped on the long U-shaped.

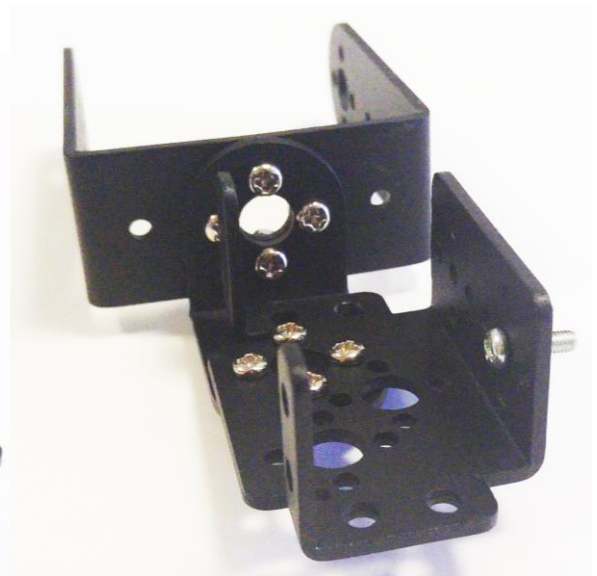
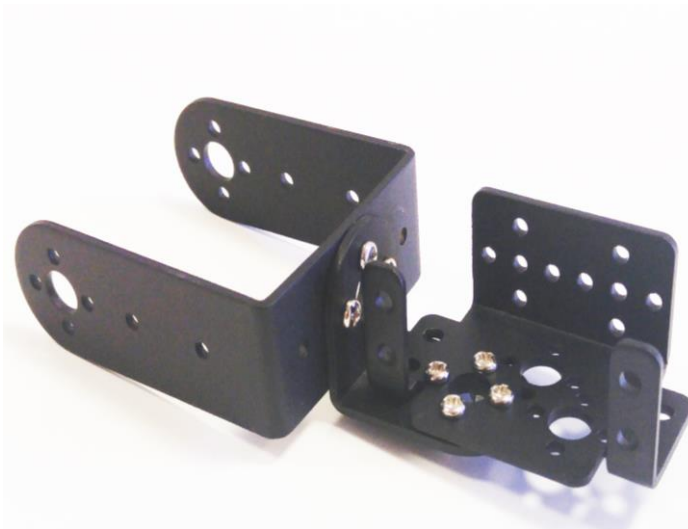




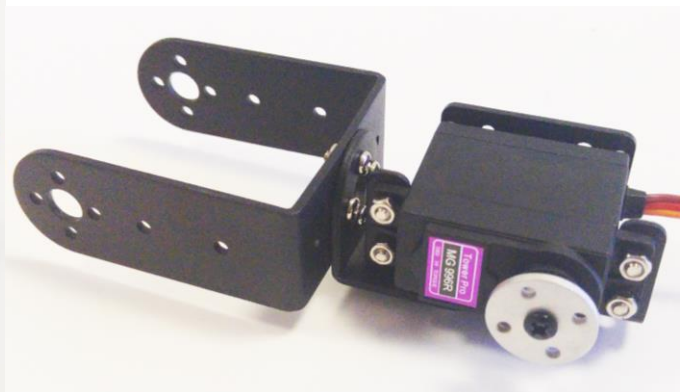
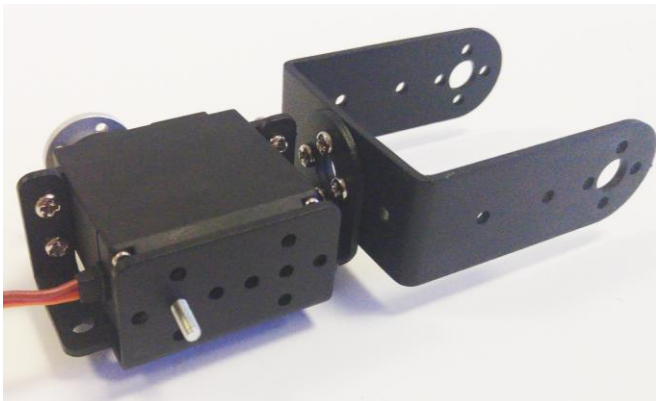
The seventh step, fix the L-shaped on the long U-shaped.



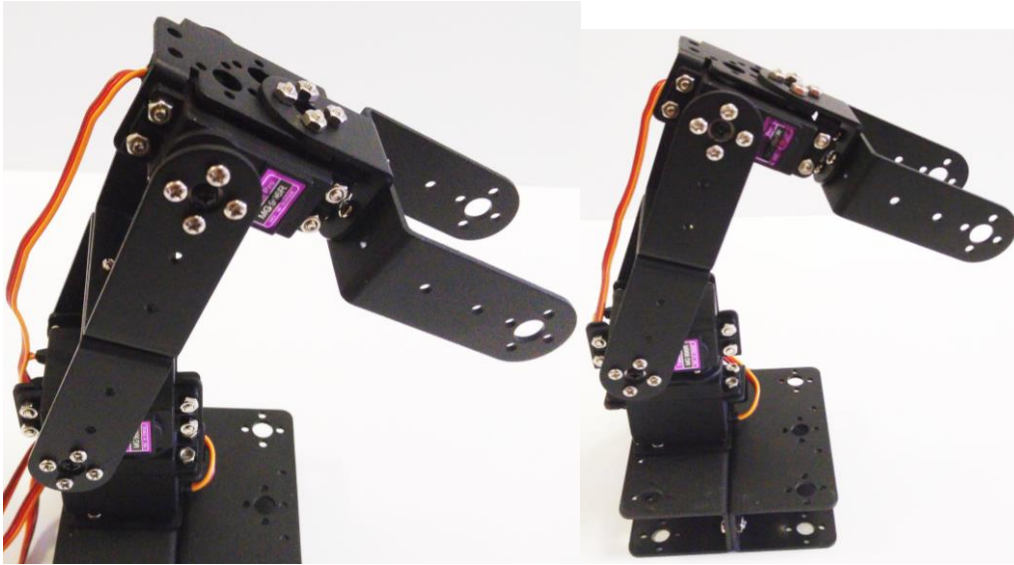
The eighth step, fix the Multi-bracket on the L-shaped. And fix a M3\*10 screw.



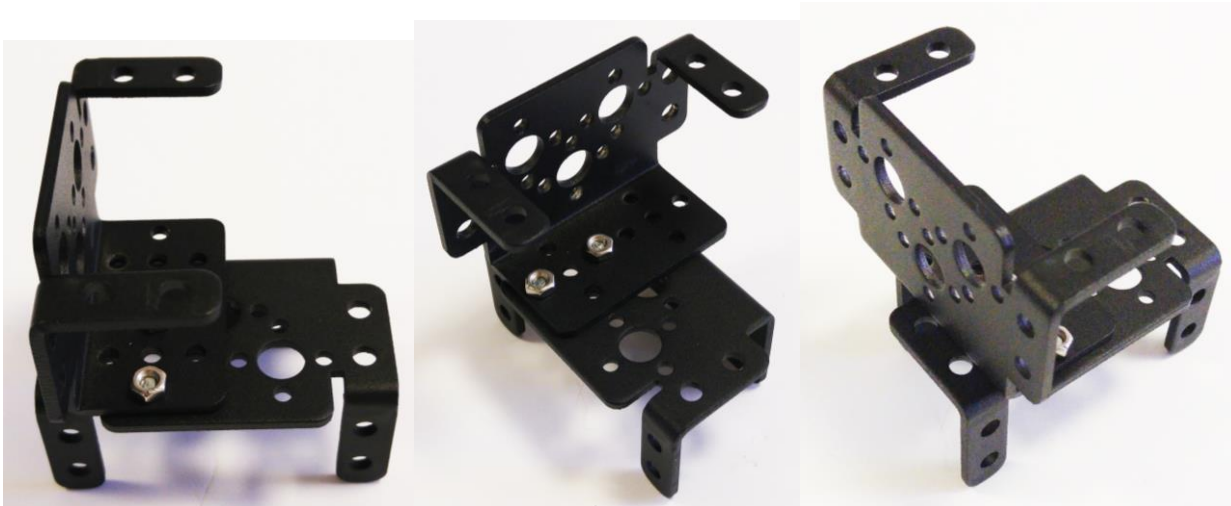
The ninth step, fix the servos.



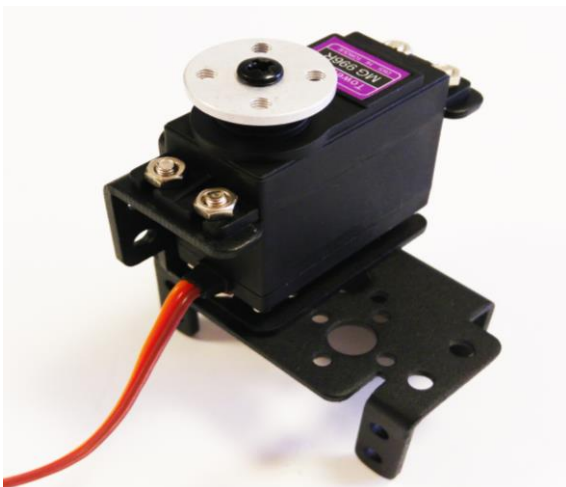
Put them together. And fix the other side bearing.



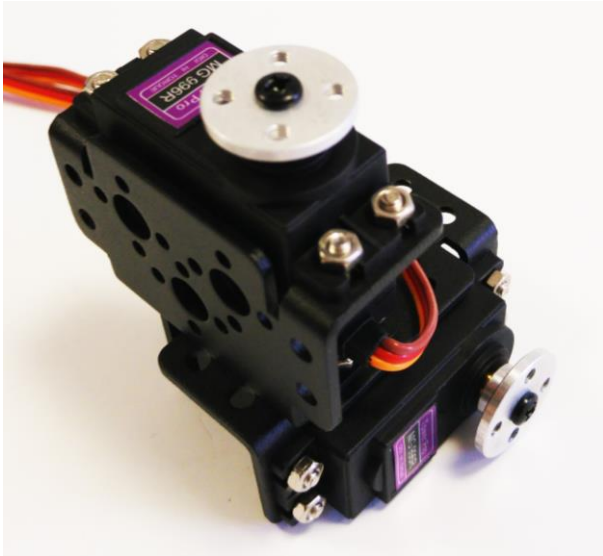
Fix the 2 Multi-bracket together (the screw is M3\*6).



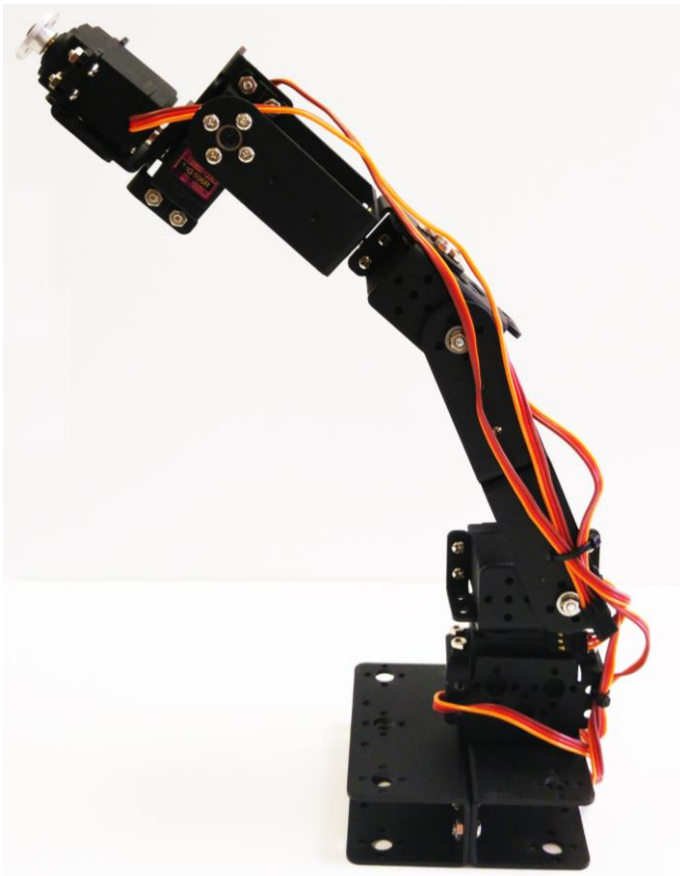
Fix the servos on the Multi-bracket (the screw is M3\*10).



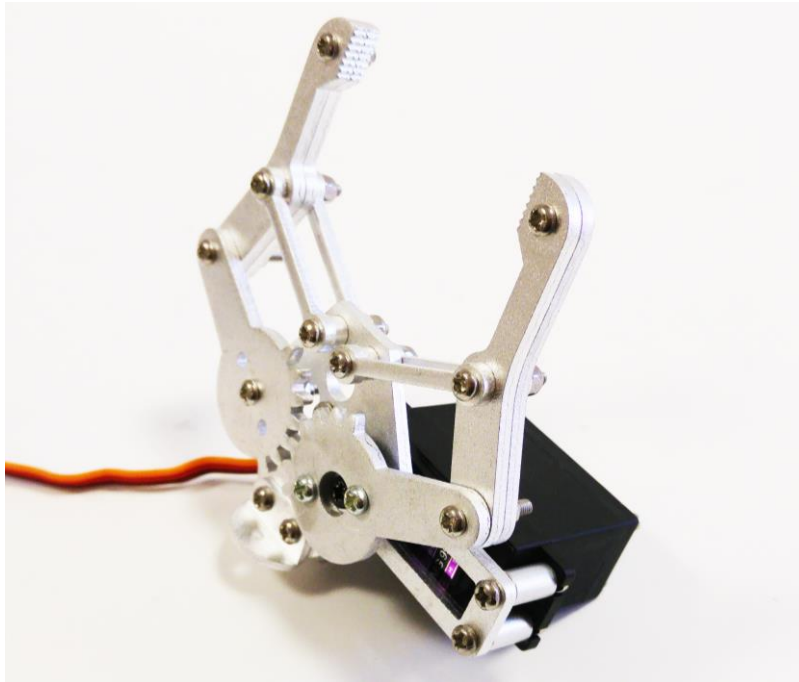
**Fix the servos under the Multi-bracket.**



**Fix them together.**



**Fix the servos and servos base on the Claws. (M3\*6)**



**Fix the Claws on the mechanical arm.**

